

**Product Overview** 

English

# Seventh Axis

## **Advantages**

### Increase a robot's range of motion.

By utilizing a shuttle system, a robot can be moved over long distances with a high range of dynamics. Available in 7 different sizes, Rollon Seventh Axis is easy to integrate and can move any type of robot weighing up to 2000 Kg.



### Protection for every work environment

High quality components

Designed with carefully selected high quality components: tempered racks with helical

teeth, rails with recirculating rollers and

planetary or hypoid bevel gearboxes.



### **Easily integrated** with any type of robot

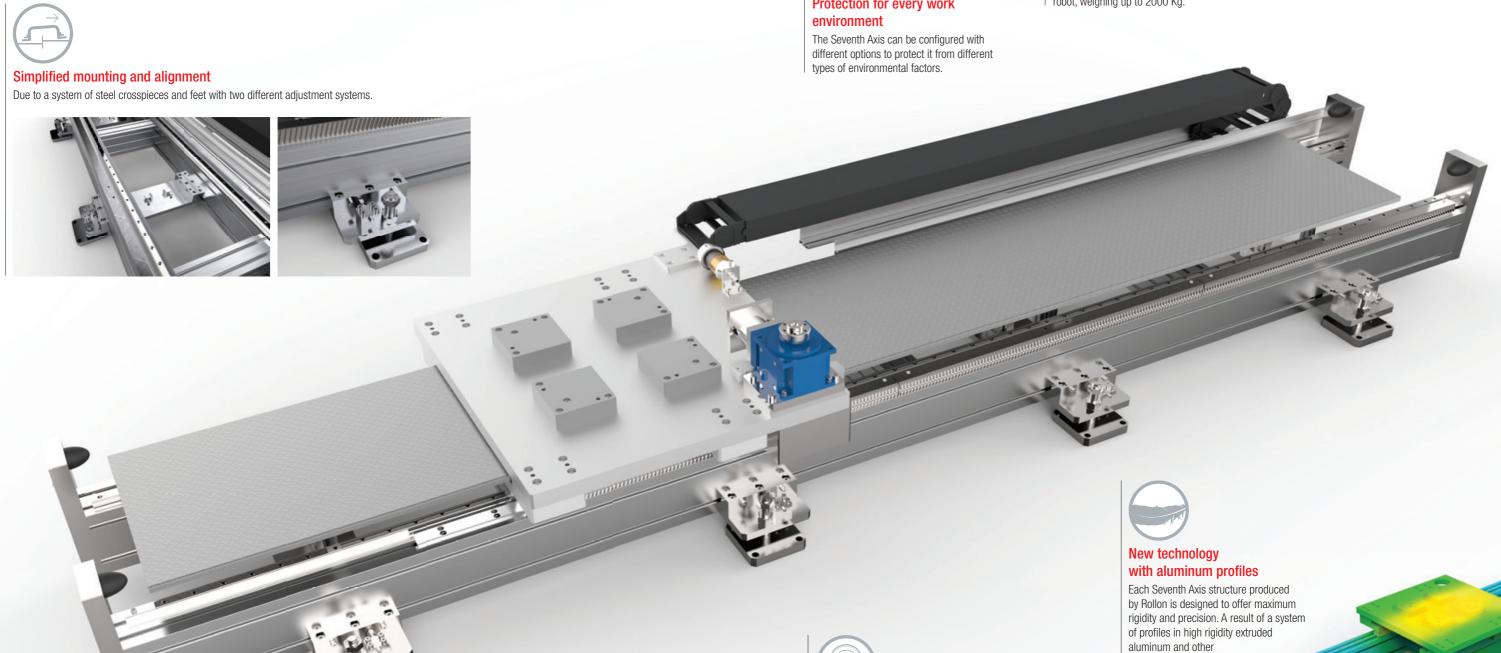
A complete range of 7 different sizes guarantees simple integration for any type of robot, weighing up to 2000 Kg.

connecting crosspieces.



# Reliability backed by decades of

Seventh Axis by Rollon was created from 40 years of expertise in designing and producing linear motion systems.

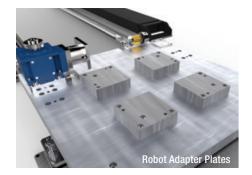


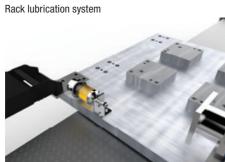
**Potentially infinite strokes** 

Thanks to jointable, self-centering inserts.

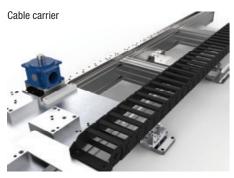
## **Components and Accessories**





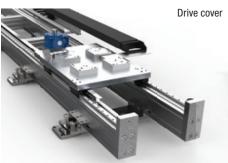




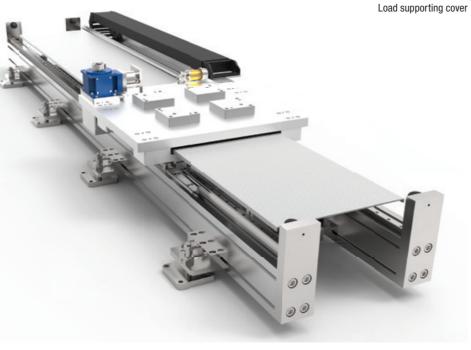


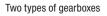




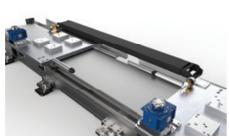








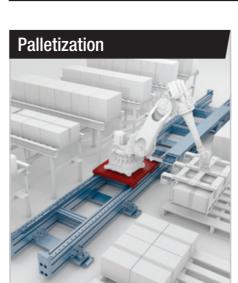


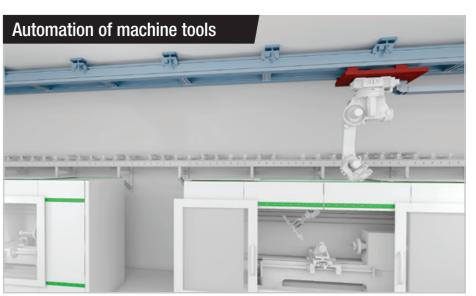


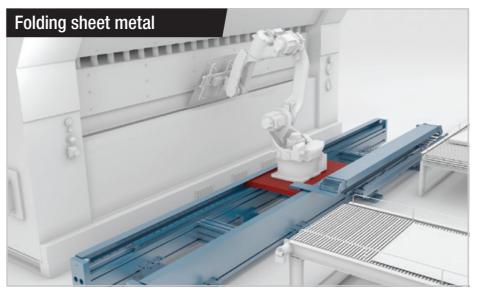
Additional carriages with anti-collision systems



# **Examples of Applications**













# Seventh Axis

# **Technical Features**



Reference		Section		Drive		Anti-corrosion	Protection			Size	Number of	Load capacity with high	Load capacity with low	Maximum speed	Maximum acceleration	Repeatability		Examples of Robots***
Family	Product	Rollers	Ball Bearings	Rack	Belt		Drive	Drive and rails	Load supporting cover		profiles	dynamics* [Kg]	dynamics** [Kg]	[m/s]	[m/s²]	[mm]	stroke [mm]	
Seventh Axis	SEV220-1					•	√			220X100	1	15	50	3	4	+/-0,05	6000	MITSUBISHI RV-2S NACHI MZ04
	SEV80-2		Example 1		Onnonnono Ond bud	•	V	<b>√</b>		80x80	2	25	100	3	4	+/-0,05	6000	FANUC LR Mate 200 MITSUBISHI RV-5F, RH-3FH COMAU Rebel S6, Racer 5 NACHI MZ07
	SEV280-1					•	$\checkmark$	V	V	170x280	1	50	300	3	4	+/-0,05	46000	ABB IRB120 FANUC LR MATE200iD KUKA KR6 Agilus MITSUBISHI RH20FH, RV-6F COMAU Racer 5
	SEV170-2					•	<b>√</b>	V	V	170x120	2	100	500	4	4	+/-0,05	46000	ABB IRB1600, IRB2600 FANUC M-10iA KUKA KR16, KR20 MITSUBISHI RV-7F, RV-20F COMAU Racer 7, SIX 6
	SEV220-2					•	$\sqrt{}$	V	$\checkmark$	220x120	2	300	800	4	4	+/-0,05	46000	ABB IRB260 FANUC M-20iA KUKA KR30 COMAU NS12, NJ16
	SEV280-2					•	V	<b>V</b>	V	280x170	2	500	1200	3	3	+/-0,05	46000	ABB IRB460 FANUC M-710iC KUKA KR30, KR60 COMAU NJ40, NJ60
	SEV360-2	filling Tilling				•	$\sqrt{}$	V	V	360x200	2	800	2000	2	2	+/-0,05	46000	ABB IRB460, IRB6620 FANUC R2000iC 165F KUKA KR QuanteK 120-150 COMAU NJ130 2.6

The data shown must be verified on the basis of the application.

\* The values shown refer to the maximum dynamics reported in this table. The load capacities refer to floor mount version.

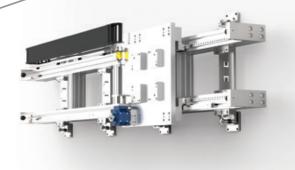
\*\* The load capacities refer to floor mount version. For more information, contact the Rollon technical office.

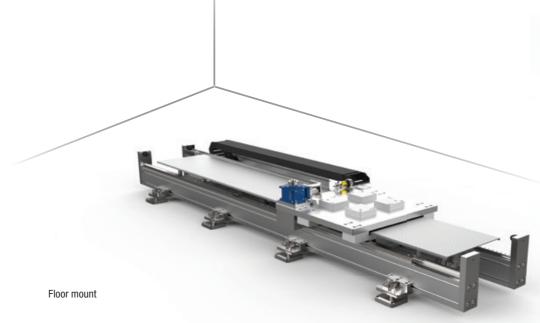
\*\*\* Robot example mentioned are approximate. For a correct choice and size of the robot contact the Rollon technical office.

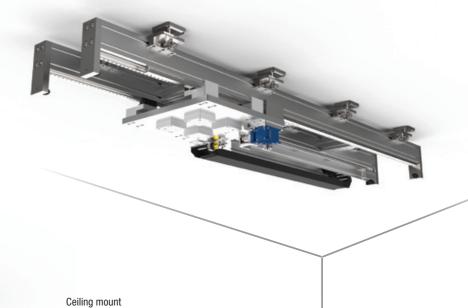
Wall mount

**Mounting Options** 











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